# Meeting Minutes: Abstract Environment API, Map Layer 1, 26.04.2021

#### Common

Compile-time vs. Run-time MantleAPI.

#### Mathematical based types: vector, point, polygon etc.

- As close as possible to OSI standard.
- ABI compatible. Cast should be possible between OSI and MantleAPI types.
- Basic types will be provided and declared in MantleAPI.
- Additional requirements will be communicated to OSI. Inspect OSI types.
- Distinguish between types and algorithms.
- Examine possibility to use of open source libraries in MantleAPI.

### Map based types/coordinate systems: road/lane positions etc.

• Map types for Lane and Road based on OpenDRIVE specification. No relation between them (inheritance etc.). Align with Andreas Bauer.

### Converter, Microscopic Queries

- Classes/interfaces for different queries/converters (currently ICoordConverter and ILaneLocationQueryService)? -> Decision: One interface/class per cluster.
- Conversion of different road types (ICoordConverter):
  - Road -> Lane
  - Road -> Inertial
  - Lane -> Road
  - Lane -> Inertial
  - o Inertial -> Lane
  - Inertial -> Vector(Lane)
  - o Inertial -> Road
  - o Road -> Lane
  - Road -> GPS
  - o Lane -> Road
  - Lane -> GPS
  - GPS -> Lane
  - O GPS -> Road
  - Elaborate a sophisticated C++ query method.
- Road Queries:
  - Road Curvature
  - Lane Curvature

- Road h, p, r (normal vector)
- o Lane h, p, r
- Road h', p', r' (e.g. yaw rate)
- Road/Lane friction
- Road/Lane z-value
- Lane width
- ... (Complete in course of development)
- One query per road/lane of e.g. heading or just one and use converter.

## Macroscopic Road/Lane Queries

- Route,
- Graph:
  - o Navigational aspects (Shortest path etc.), Reference line specific
  - Lane: Successor, Predecessor (Longitudinal)
  - Lane: Adjacent relationships (left, right), logical, e.g. in driving direction?
  - Lane properties (edge weights): Traffic signs, lane markings, length etc.