AMALTHEA4public 3th Advisory Board Meeting



Embedding APP4MC in a Systems Engineering development process

16 February 2017 Munich, Germany





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Embedding APP4MC in a Systems Engineering development process



- Overall goal until end of the project: Provide an example on how APP4MC is embedded in an existing toolchain
 - Based on a fictional driver assistance system
 - Based on open source tools (easy replicability)
- Subgoals / what does embedding mean?:
 - Showcase trace link management with Capra
 - Showcase a model transformation from software design to APP4MC
 - Showcase how safety requirements can be handled
- Goals for today:
 - Showcase the current state of development
 - Discussion and feedback

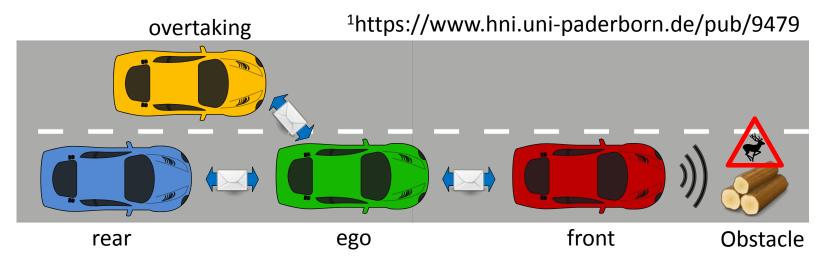


EBEAS¹ Overview



(Emergency Braking & Evasion Assistance System)

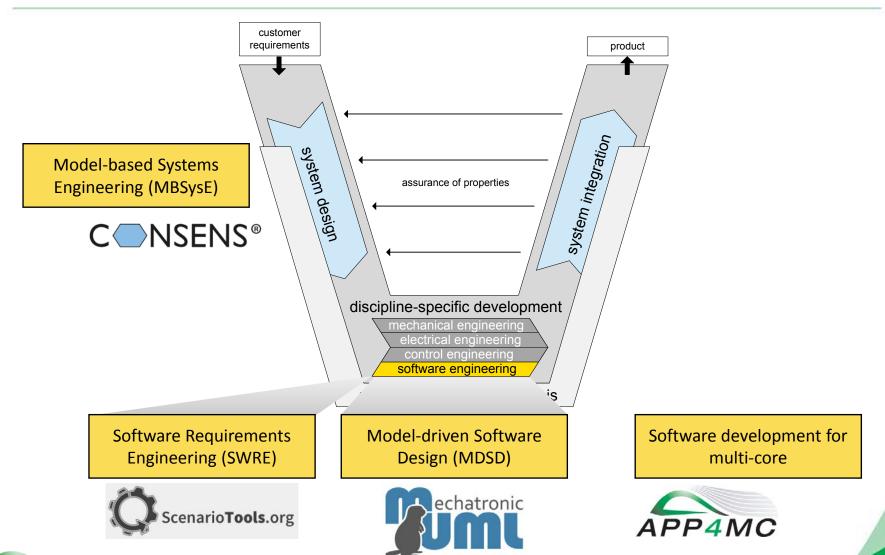
- Four autonomous, Car2Car-capable vehicles on a two-lane street
- Front vehicle detects an obstacle and has to perform an emergency brake
- Front vehicle notifies the following traffic which in turn has to handle the overall situation (depending on distances, available space, ...)
- Scope/SUD: ECU which realizes the intended functionality (i.e., Systems- & Software Engineering)







Development process overview







EBEAS Model Landscape

Model-based Systems Engineering (MBSysE)











Active Structure



App. Scenarios



Beh. States



Requirements



Beh. Sequences



Functions



Initial SW-Arch.

Formal Req.



Simulation

Consist. Checks

Software Requirements Engineering (SWRE)







SW Architecture

Real-time Beh.



Model Checking

SW Allocation

Model-driven Software Design (MDSD)



Software development for multi-core









EBEAS Model Landscape (today)

Model-based Systems Engineering (MBSysE)



























Initial SW-Arch.

Formal Req.



Software Requirements Engineering (SWRE)





Scenario**Tools**.org



SW Architecture

Real-time Beh.



Model-driven Software Design (MDSD)



Software development for multi-core

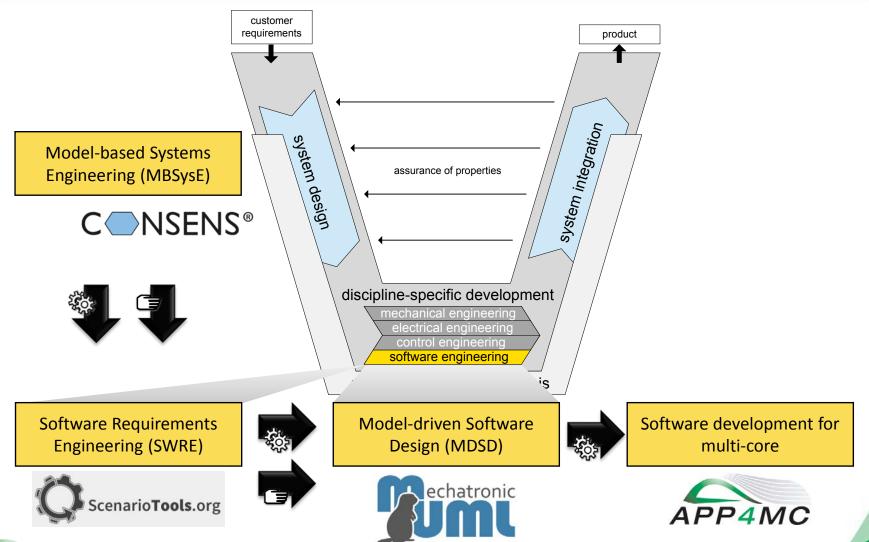








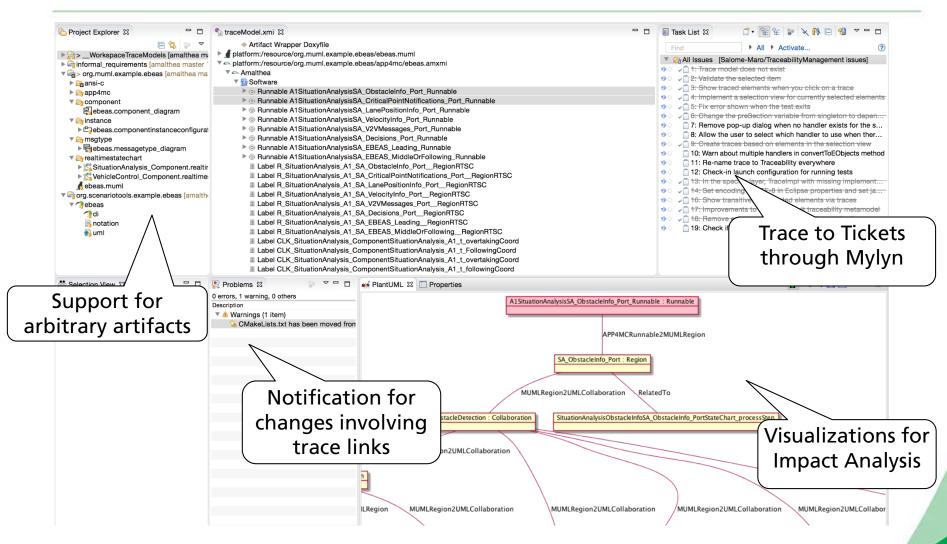
Research at Fraunhofer IEM









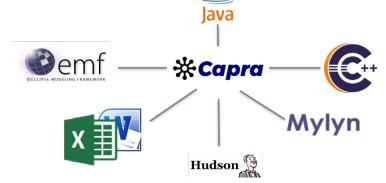


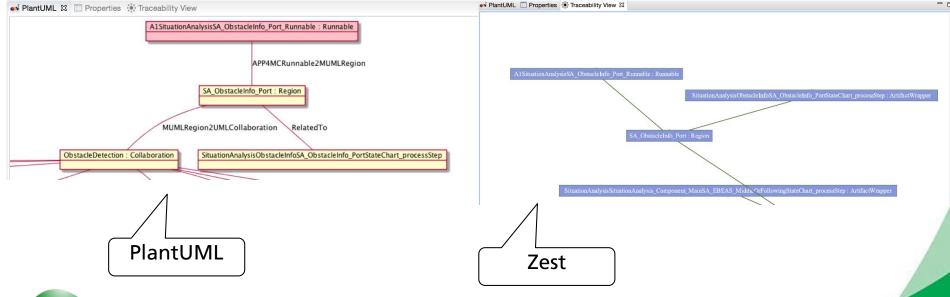




Capra - Flexibility and Extendibility

- Ability to define a custom traceability metamodel
- Ability to add more artifact handlers
- Ability to extend the Visualization

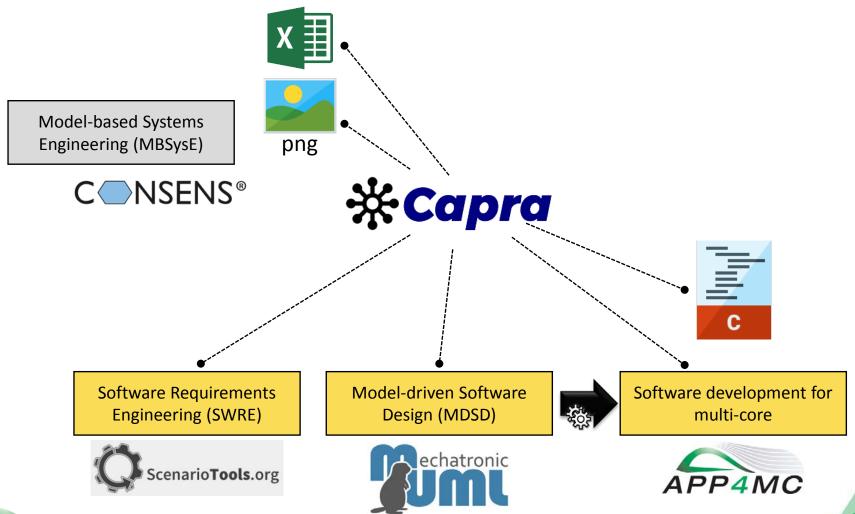






Scope of the demonstration Tracelink management with Capra

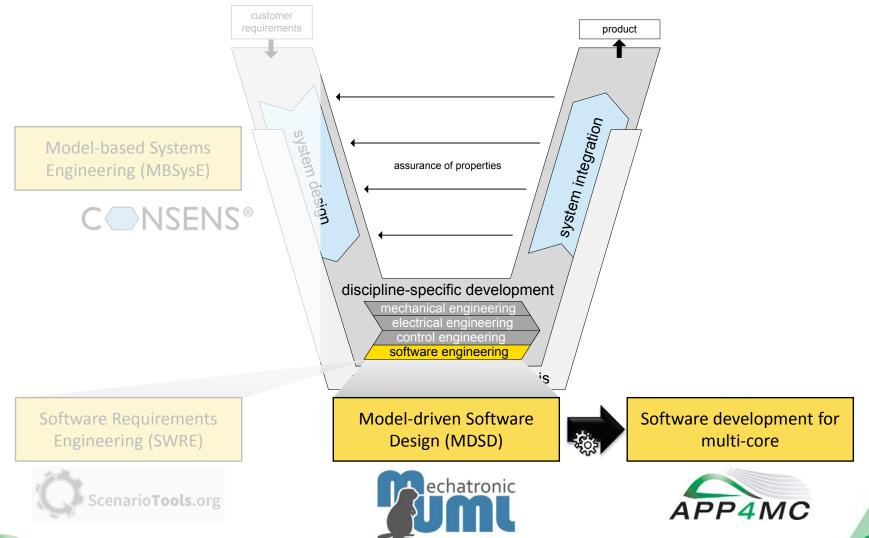






Scope of the demonstration Model transformation M-UML → APP4MC







Scope of the demonstration Model transformation M-UML → APP4MC





Safety-critical



Real-time Requirements

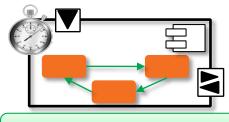


Limited Resources



Multi-core Environments





Formal Software Model

How to **execute** the software **correct** and **efficient** without violating safety requirements?

- Enable Parallel Execution
- Respect Semantics and Model Checking Assumptions
- Respect Platform Constraints

Model Checking

"Start evading within 25 milliseconds after receiving the acknowledgement."





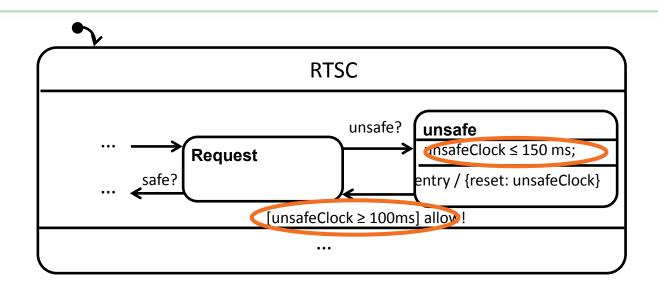
Real-time Scheduling

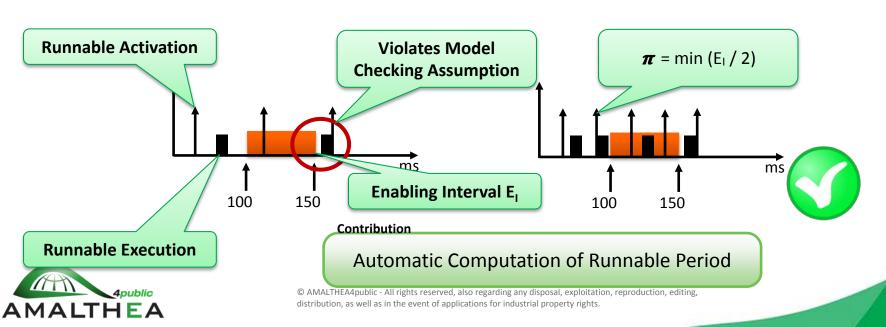
















- EBEAS example
 - CONSENS models in Papyrus
 - Complete models in ScenarioTools and MechatronicUML
 - Deployment on the RC-Car / Rover (ambitious ©)
- MechatronicUML → APP4MC transformation
 - Transformation of additional model elements: components, hardware
 - Utilization of component allocation information in Partitioning and Mapping





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Chalmers | Unversity of Gothenburg Department of Computer Science and Engineering Software Engineering Division https://chalmers.se/cse

https://eclipse.org/capra/

