

### Eclipse eCAL - overview and deep dive "Distributed Recording"



### What's that ? Eclipse eCAL<sup>™</sup> ?



enhanced Communication Abstraction Layer

**Communication Stack** 

2016 – Continental Automotive R&D

2019 – OpenSource under Apache 2

2022 – Eclipse SDV Project



### Prototyping AD vehicle systems



Programming Languages

**Operation Systems** 

Hardware Targets

Interfaces

Acceptance



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### Prototyping AD vehicle systems – Bonus level "Data Management"





Massive Data

**High Speed Transmission** 

**Distributed Computing System** 

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Monitoring

Recording

## How can eCAL handle this?



### **Designed for Multicore / Multihost Systems**

- eCAL distributes everything
  - Sensor Interfaces
  - Software Components
  - Ecosystem Applications
- eCAL is highly optimized on performance
  - C++ core
  - Interprocess Shared Memory Support
- eCAL has powerful tools
  - Monitoring, Recording, Replay, System Boot/Shutdown
  - Distributed Recording Concept unique selling point ③





# What's behind it? The architecture.



### Architecture – Core

- supports POSIX as well as Windows operating systems
- supports different transport protocols
  - inter-process communication: shared memory
  - inter-host communication: udp multicast / tcp
- supports different serialization formats
  - google::protobuf
  - capnproto
  - google::flatbuffers, messagepack, json ...
- supports publish / subscribe and client / server pattern
- brokerless dynamic design



Transport Layer

**Operating System** 

Hardware Target System



### Architecture – Languages and Tools

- Ianguage bindings for C, C++, C#, Python, Rust, Go, M-Script, Simulink
- shipped with eco system tools for
  - live monitoring of all software component interfaces
  - orchestrated, distributed message recording
  - message replay real-time or stepwise
  - automated component start, stop and supervising
  - all tools realized as command line and GUI application







# From theory to practice. Typical use cases.



### AD Demo Vehicle Setup

НМІ		Lane Detection	Vel Local	nicle ization	Driving Functions	
	a manage and					
Camera / Radar Interfaces		CAN Gateways			Backend Interface	
eCAL Live Data Monitor		eCAL Recording Orchestrator				
		Recording Srv.	Recording Srv.	Recording Service		
eCAL runtime						
Windows 10	QNX	Ubuntu 18.04	Ubuntu 18.04	Ubuntu 20.04		
Dev. Control PC	Speedgoat	NVIDIA Tegra A	NVIDIA Tegra B	MultiCore HPC		



### Validation of 3 Software Components





### **Deep Dive "Data Recording"**



### AD Recording – Problem Statement



Throughput

Distribution

Postprocessing

Persistency

**API's** 



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# **Classic Recording Approach**



### The magic, single (hardware) recording device





#### Disadvantages:

Bottlenecks everywhere

Expensive hardware

Sensorics pass-through

High configuration effort



## eCAL's Distributed Recording Solution



### eCAL's Distributed Recording Solution





#### Recording:

Interface abstraction

Distributed recording instances

Orchestration / synchronization

Scalability / cost reduction



### eCAL's Distributed Recording Solution



# Aggregation:

Integrated FTP clients

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Automated reassembling

Different storage targets

Current format HDF5



## Live Demo "Recording in Action"





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# **Remember your questions** <sup>(2)</sup>



# Summary





eCAL is designed for autonomous driving applications

eCAL combines modern communication patterns with state-of-the-art message protocols

eCAL has powerful tools for rapid prototyping

eCAL is open source since 2019 and part of the Eclipse family since 2022 ©





# Thank you!

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